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## Small World An algorithmic perspective

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Problematic networks

The navigable network: r = 200000

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The navigable network: r = 2Balance in all things

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Small-World phenomenon

# From legends to theory

- The small-world phenomenon: in a social network each pair of nodes is connected with a fairly short path.
- ► First significant scientific attention in the 1960's.
- Milgram *et al.*: people are connected to each other with paths of length six on average.
- ▶ Path lengths give the average diameter of the network.
- The claim is a strong requirement for the denseness and the homogeneity of the network.

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Small-World phenomenon

## First attempts on an explanation

- Pool and Kochen gave ground to the claims already before Milgram's tests.
- ► They showed that random graphs have very often short diameters, of size O(log n).
- ► They didn't use transitivity: if Anna and Bob both know Cecil, then Anna and Bob probably know each other too.
- But this may easily lead to a strongly-clustered network where the claim can't hold.

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Small-World phenomenon

#### A new model emerges Searching a good balance

- In 1998 Watts and Strogatz published a network model that tried to balance between these two problems.
- ► They created networks with both local and long-range links.
- ► Local links used the *K*-closest-neighbours rule and the long ones were chosen uniformly at random.
- This seems to match the ideas of transitivity and homogeneity quite well.
- ► This model actually fits to many real-world networks.

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Small-World phenomenon

### Twisting the question Not just why, but how?

- The random graph theory successfully explains the existence of short diameters.
- But in Milgram's tests the letters actually found the recipients in those six steps.
- ► How are strangers able to find these short paths with their very limited information?
- The graph is huge and quite dense. There's a whole lot of paths and most of them cannot be short.
- Thus the latent information of the network must be more important than it seems at first.

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Small-World phenomenon

### Defining the model Idea of Kleinberg

- Let the edges be directed.
- ► Model the network as a two-dimensional *n* × *n* grid and use the Manhattan distance.
- ► Each element has an outgoing edge to each node within distance p ≥ 1.
- Each element also has q randomly selected long-range outgoing edges.
- ► The length of these long-range edges will be decisive.

Problematic networks

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Small-World phenomenon

# Pin-pointing the problems

- ► If we just select the long-range edges uniformly at random, there will be no small-world.
- Look at the nodes at most  $\sqrt{n}$  away from target *t*.
- Probability of hitting one of them is  $1/\sqrt{n}$ .
- It would take  $\mathcal{O}(\sqrt{n})$  steps to get there in average.
- ► The problem here is that the closer we are to *t*, the more probably the long-range edges will take us to totally elsewhere.

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Small-World phenomenon

### Defining the model continued Selecting the long jumps

- ► Say we are selecting the long-range edges of u. A node v will be selected with probability proportional to d(u,v)<sup>-r</sup>.
- ▶ This *r* will be the *concentration exponent*.
- ► The model now has parameters *p*, *q* and *r*, but only *r* has any real effect on the model's behaviour.

Problematic networks

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# Defining limits for a solution

- The goal is to examine decentralized algorithms.
- An entity knows only what it has been told.
- It knows the location of the target, its own links and the grid structure of the lattice.

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# Networks without a small-world

- When would there be some problems?
- ► For large *r* this might be quite obvious.
- ► In that case the close neighbours of *t* will be proportionally quite far away from everything else.
- Therefore getting to the neighbourhood will easily take too long, because the long links are not long enough.

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# What about small r's?

- ► In the case of a small *r* there should no problems with converging on the target.
- So why shouldn't it work?
- Problem is that we need precision to hit the proportionally small neighbourhood.
- Small *r* makes the algorithms to easily overshoot.
- ► This means that the long links don't give enough advantage.

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Problematic networks

The navigable network: r = 200000 Summary

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Too fast, too imprecise: r < 2

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Too fast, too imprecise: r < 2

#### Seeking the chokepoint Link lengths

- Remember the uniform case r = 0.
- The closer we are, the farther the graph will take us.
- Probabilities of long links should be too large and short links too small:

$$\sum_{\nu \neq u} d(u, \nu)^{-r} \geq \frac{n^{2-r}}{(2-r)2^{3-r}}.$$

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Too fast, too imprecise: r < 2

### Seeking the chokepoint Neighbourhood

- Select a neighbourhood *U* for *t* with radius  $pn^{\delta}$ .
- We get easily  $|U| \leq 4p^2 n^{2\delta}$ .
- Next let's calculate how easy it is to find a long-range link to U in λn<sup>δ</sup> steps.
- ▶ Define this event to be *E*.

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► In a certain step we'll find a long link to *U* with probability at most

$$\frac{q|U|}{\frac{1}{(2-r)2^{3-r}}n^{2-r}} \le \frac{(2-r)2^{5-r}qp^2n^{2\delta}}{n^{2-r}}.$$

• Doing this in  $\lambda n^{\delta}$  steps thus has probability

$$P(\mathcal{E}) \leq \lambda n^{\delta} \frac{(2-r)2^{5-r}qp^2n^{2\delta}}{n^{2-r}} \leq \frac{1}{4}$$

when selecting  $\lambda$  suitably and  $\delta = (2 - r)/3$ .

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## Scrapping parts

- ► Next we'll forget the not-so-obviously problematic parts.
- Let  $\mathcal{F}$  be the event for  $d(s, t) \ge n/4$ .
- Easily one sees that  $P(\mathcal{F}) \ge 1/2$ .
- Now we can conclude that

$$P(\overline{\mathcal{F}} \vee \mathcal{E}) \leq \frac{1}{2} + \frac{1}{4} \implies P(\mathcal{F} \wedge \overline{\mathcal{E}}) \geq \frac{1}{4}$$

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### Scrapping parts continued

- Suppose  $\mathcal{F} \wedge \overline{\mathcal{E}}$ .
- Then  $d(s,t) \ge n/4 > p\lambda n^{\delta}$ .
- Getting to t in λn<sup>δ</sup> steps requires now at least one long jump to U.
- This is a contradiction. In this case thus all paths to *t* have length more than λn<sup>δ</sup>.

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Too fast, too imprecise: r < 2

## Cleaning house

- Now we can concentrate on the substantial part of situations where we have the most problems.
- ► If *X* denotes the number of steps needed to reach *t*, then

$$E(X) \geq E(X|\mathcal{F} \wedge \overline{\mathcal{E}}) \cdot P(\mathcal{F} \wedge \overline{\mathcal{E}}) \geq rac{1}{4} \lambda n^{\delta}.$$

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# Brainstorming the solution

- ► The links should now be more tightly concentrated.
- This means that getting far will be hard.
- Our aim is to prove that most paths are much too short.

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Too introvert: r > 2

# Gathering pieces

- Let  $\varepsilon = r 2$  be the number of problems we have.
- ▶ If *v* is a long-range contact of *u* then we can easily say that  $P(d(u, v) > m) \le m^{-\varepsilon} / \varepsilon$ .
- Define  $\mathcal{F}$  and X similarly as before.
- ►  $\mathcal{E}$  will be the event that we find a link longer than  $n^{\gamma}$  in  $\lambda n^{\beta}$  steps.
- ▶ We'll progress just as we did in the *r* < 2 case.

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# Probability of $\mathcal{E}$

► The union bound will give us

$$P(\mathcal{E}) \leq \lambda n^{\beta} q n^{-\varepsilon \gamma} / \varepsilon \leq \frac{1}{4},$$

when choosing  $\lambda$  suitably and  $\beta = \varepsilon \gamma$ .

- Now we once again see that  $P(\mathcal{F} \wedge \overline{\mathcal{E}}) \ge 1/4$ .
- In that case the first λn<sup>β</sup> steps will take us only λn<sup>β+γ</sup> = λn < n/4 < d(s,t) steps closer. (Choose β + γ = 1)</p>

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• Requirements  $\beta = \varepsilon \gamma$  and  $\beta + \gamma = 1$  imply

$$\beta = \frac{\varepsilon}{\varepsilon + 1}$$
 and  $\gamma = \frac{1}{\varepsilon + 1}$ 

We achieve the desired bound using the same tricks as before:

$$E(X) \geq E(X|\mathcal{F}\wedge\overline{\mathcal{E}})\cdot P(\mathcal{F}\wedge\overline{\mathcal{E}}) \geq rac{1}{4}\lambda n^{eta} = rac{1}{4}\lambda n^{rac{r-2}{r-1}}.$$

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Balance in all things

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## Plot of the lower bounds





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Balance in all things

# Going through a phase

- ► The probability that u has v as its long-range link is at least d(u,v)<sup>-2</sup>/(4log(6n)).
- ► We say that the algorithm is in phase *j* if for the current node *u* : 2<sup>*j*</sup> < *d*(*u*, *t*) ≤ 2<sup>*j*+1</sup>.
- Suppose  $B_j$  is the set of nodes  $v : d(v, t) \le 2^j$ .
- We easily get  $|B_j| > 2^{2j-1}$  and  $\forall v \in B_j : d(u, v) < 2^{j+2}$ .
- What is the probability of changing phase?

$$P( ext{we move to } B_j) \geq rac{2^{2j-1}}{4\log(6n)2^{2j+4}} = rac{1}{128\log(6n)}.$$

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## Phase-shift

•  $X_j$  is now the time spent in phase *j*:

$$egin{aligned} E(X_j) &= \sum_{i=1}^\infty P(X_j \geq i) \leq \sum_{i=1}^\infty ig(1 - rac{1}{128\log(6n)}ig)^{i-1} \ &= 128\log(6n). \end{aligned}$$

▶ There are  $\log n$  phases in total, therefore the expectation of the path lengths is  $E(X) = O(\log^2 n)$ .

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### Reason behind the phenomenon

- The problem in the first cases was that either the closer nodes were too close or the farther nodes were too far.
- In the r = 2 case all the phases were homogeneous.
- The magic behind this is that 2 is the only exponent for which the long-range links are uniformly distributed over distance scales
- Links of length 2<sup>j</sup> to 2<sup>j+1</sup> have the same probabilities for all *j*. Thus we have enough precision in every case.

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### Summary

- In a large network one has to manage local and global relations simultaneously.
- Heisenberg uncertainty principle for networks: you can't have both at the same time, but you can trade them.
- The paper states the balance enabling a subject to grasp the whole and still observe the vicinity.