

# *Characteristics of an Analysis Method*

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# *Introduction*

- Basic concepts are presented.
- The PCA method is analyzed.
- Motivation for more sophisticated methods is given.

# Outline

**1** *Expected Functionalities*

**2** *Basic Characteristics of DR algorithms*

**3** *PCA*

**4** *Categorization of DR methods*

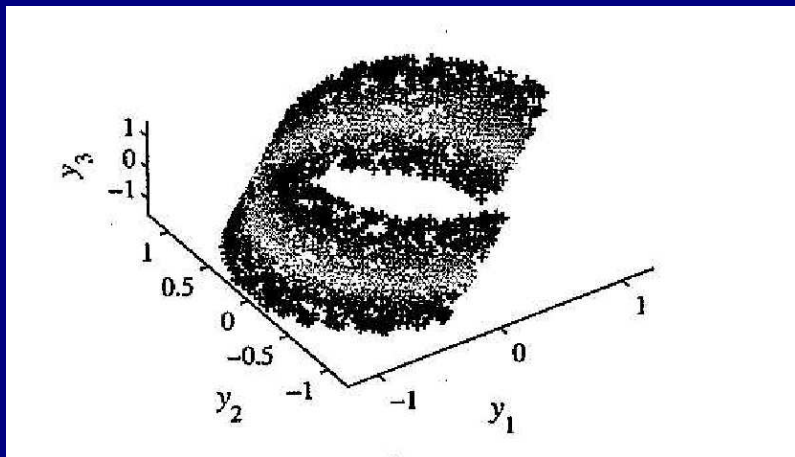
# *Basic Requirements*

- Estimation of the embedding dimension.
- Dimensionality reduction
- Separation of latent variables.

# *Intrinsic Dimensionality*

- Let us assume that the data is in  $\mathbb{R}^D$ .
- The basic assumption: the data can be embedded into  $\mathbb{R}^P$  with  $P < D$ .

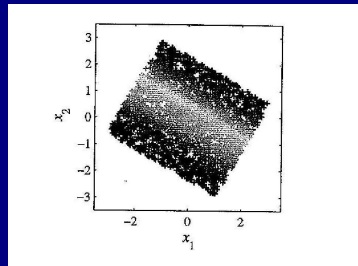
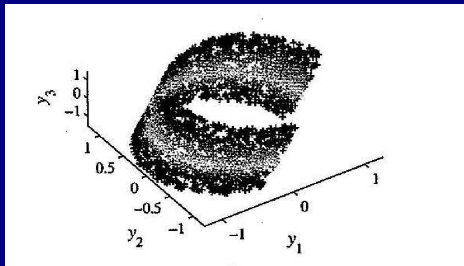
## *Example: A Low Dimensional Manifold*



# *Latent Variables vs. Dimensionality Reduction*

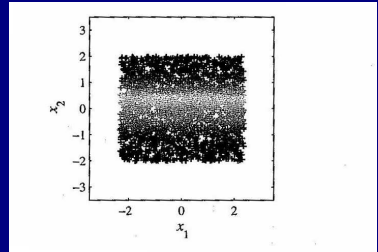
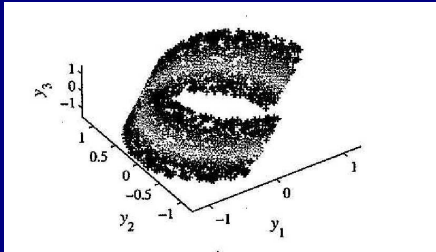
- When extracting latent variables, a model generating the data is assumed (eg. ICA).
- The embedding into a lower dimensional space is done under this constraint.
- Dimensionality reduction is easier: any low dimensional representation is a solution.
- DR is less interpretable?

# Example: Dimensionality Reduction





# Example: Recovery of Latent Variables



- Dimensionality reduction under an independence constraint.

# *Fundamental Issues*

- Many dimensionality reduction algorithms assume that the data is generated by a model.
- For example, in PCA it is assumed that a number of latent variables explain the data in a linear way.
- For the same model, different algorithms are possible.

# *The Criterion*

- The dimensionality reduction is often done using a criterion that is optimized.
- One possible idea is to measure distance preservation.
- One may either try to preserve the distances between points or alternatively the topology.

# *Projection as a criterion*

- Let  $\mathcal{P} : \mathfrak{R}^D \rightarrow \mathfrak{R}^P$  be a projection.
- $\mathcal{P}^{-1}$  denotes the reconstruction  $\mathfrak{R}^P \rightarrow \mathfrak{R}^D$ .
- A common criterion in dimensionality reduction is

$$E[\|y - \mathcal{P}^{-1}\mathcal{P}(x)\|^2].$$

# *Derivation of PCA (1)*

- The basic model behind PCA is

$$y = Wx$$

with  $y$  a random variable in  $\mathfrak{R}^D$  and  $W$  a  $D \times P$  matrix.

- The sample  $(X_i, Y_i)_{i=1}^N$  is available; mean centering is assumed.
- Normalization/scaling is done according to prior knowledge.

## *Derivation of PCA (2)*

- Assume that  $W$  has orthonormal columns.
- The projection criterion leads to

$$\min_W E[\|y - WW^T y\|^2].$$

- This corresponds to finding the subspace which allows best possible reconstruction.

## *Derivation of PCA (3)*

- The optimization problem can be written equivalently as

$$\max_W E[y^T W W^T y].$$

- Let  $Y$  be the matrix of samples as column vectors.
- Empirical approximation leads to

$$\max_W \text{tr}[Y^T W W^T Y].$$

## *Derivation of PCA (4)*

- Singular value decomposition  $Y = V\Sigma U^T$  yields

$$\max_W \text{tr}[U\Sigma V^T W W^T V\Sigma U^T].$$

- The solution is taking the columns of  $V$  corresponding to the largest singular values, which can be written as  $W = VI_{D \times P}$ .
- The reconstruction error depends on the singular values  $\sigma_{P+1}, \dots, \sigma_D$ .



## *Relation to the Covariance Matrix*

- Let  $C_y$  be the covariance matrix of the observations.
- Finding the projection  $V$  is equivalent to finding the eigenvectors  $V_1, \dots, V_P$  corresponding to the biggest eigenvalues.
- The eigenvectors are the directions of maximal variance.

# *Choosing the embedding dimensionality*

- A simple method is to plot sorted eigenvalues.
- After some point, the decrease is negligible.
- This often fails; other choices include Akaike's information criterion and other complexity penalization methods.
- It is also possible to put a threshold: for example, require that 95% of the variance is preserved.

## *Example: Determination of Intrinsic Dimensionality*

Choose  $X \sim N(0, I) \in \mathbb{R}^2$ ,

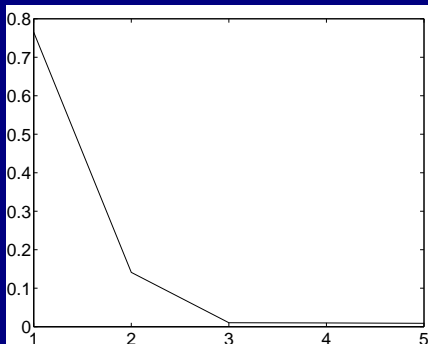
$$A = [0.1 \ 0.2; 0.4 \ 0.2; 0.3 \ 0.3; 0.5 \ 0.1; 0.1 \ 0.4]$$

and

$$Y = AX + \epsilon$$

with  $\epsilon \sim N(0, 0.1I)$ .

## *Example: Determination of Intrinsic Dimensionality (2)*

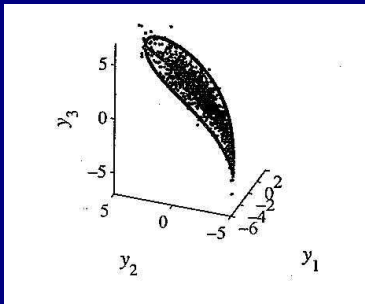


*Figure:* Eigenvalues of the covariance matrix.

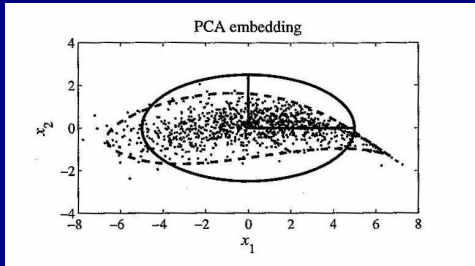
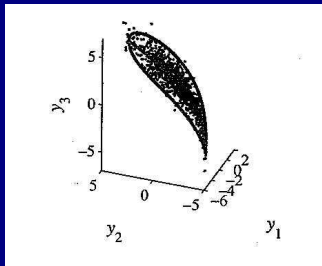
- The first two contain most of the variance.

# PCA for nonlinear data (1)

■ The model:  $y = \begin{bmatrix} 4 \cos(\frac{1}{4}x_1) \\ 4 \sin(\frac{1}{4}x_1) \\ x_1 + x_2 \end{bmatrix}$ .



## PCA for nonlinear data (2)



- The reconstructed surface would be a plane.

# *DR vs. generative (latent variable) models*

- It is possible to model the data using latent variables and estimate the parameters.
- In practice, it is simpler to directly learn a projection.

# *Local Dimensionality Reduction*

- A nonlinear manifold is locally approximately linear.
- It is possible to derive a local PCA as a generalization to the nonlinear case.



# *Other Issues*

- Batch vs. online algorithm
- Local maximas  $\langle - \rangle$  global optimization (PCA)

# *Conclusion*

- Many dimensionality reduction methods are based on the assumption that the data is approximately on a manifold.
- PCA solves the linear case, but fails in nonlinear problems.
- Thank you for your attention.